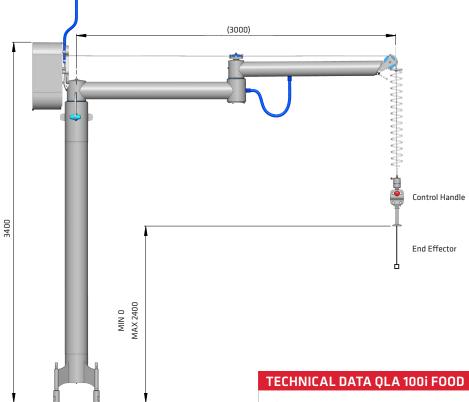
### QUICK-LIFT ARM QLA100i FOOD SPECIFICATIONS

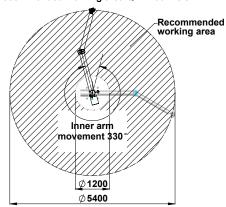


# Quick-Lift Arm

## **QLA 100i FOOD**



#### Recommended working area QLA 100i FOOD



### Options

- Control handle for pneumatical clamping OR control handle for mechanical clamping.
- Higher surface finish on pillar and arms, Ra 1.6 instead of standard Ra 3.2.
  - **Note:** Control handle surface finish is always higher (Ra 1.6).
- Extra grinding process on the welds.
  - Note: All welds are free from cracks and polished to chosen Ra value.
- Stainless steel cover for motor unit to minimize time for daily cleaning.
- Good grade stainless steel fasteners.
  Note: Standard fasteners are stainless steel A4 quality, all external hex head for easier cleaning.

Lifting capacity	WLL 100 kg including the weight of the control handle and the end effector.
Working area	Max recommended working radius = 2.7 m from pillar.
Stroke length	2.7 meter
Lift motor	Highly efficient servo-controlled motor. Corrosion protected.
Power supply	230V, 50-60 Hz 1-phase with protective ground, 10A fuse
Power consump.	Typical average 100 W over a work cycle.
Arm & Pillar	Round polished stainless steel tube design with no horizontal areas for water run-off and easy cleaning/sanitizing.
Cleaning & Sanitizing	Withstands most common cleaning and sanitizing agents. Can be hosed down. NO high pressure washing
Environment	Withstands continuous 100% humidity (RH). IP56 design and heated electronics.
Temperature range	0° to +40° C On request -20° to +10° C
Attachment	Raised pillar lower end for easy cleaning. Adjustable feet for slanting floor. Optional shorter or longer pillars
Manoeuvring	Manoeuvring is done with Binar Handling's patented control handle. Only a small force is needed to engage the up/down motion. When the operator let go of the handle, the up/down motion is immediately stopped.
End effector	End effectors are designed to fit customers need. Extenal sensor signals can be used for optimum functional ity and safety.

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